

**Question:**

The matrix $A_{3 \times 3}$ has eigenvalues $\underline{1}$, $\underline{0}$ and $\underline{-1}$ with corresponding eigenvectors $\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$, $\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ respectively.

- (1) Determine whether A is singular.
- (2) Determine whether A is diagonalizable.
- (3) Find the matrix A .

**Discussion:**

- (1) As 0 is an eigenvalue of A , A is singular.
- (2) As A has 3 distinct eigenvalues, then A has **3** linearly independent eigenvectors, hence, A is diagonalizable.

Remark: based on the first two parts above, you may see there's no relation between the singularity and diagonalizability of matrices.

(3) **Method 1** definition of the diagonalizable matrix.

Since A is diagonalizable, which means,

$$P^{-1}AP = D, \text{ where } P \text{ is non-singular.}$$

$$\begin{aligned} \text{So } P(P^{-1}AP)P^{-1} &= PD P^{-1} \Rightarrow (PP^{-1}) \cdot A \cdot (PP^{-1}) = PDP^{-1} \\ &\Rightarrow A = PDP^{-1} \end{aligned}$$

We can use the three eigenvectors to form the matrix P ,

$$P = \begin{pmatrix} 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}$$

and use the corresponding eigenvalues to form the matrix D ,

$$D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

So the required matrix A is given by,

$$\begin{aligned} \mathcal{A} &= PDP^{-1} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}^{-1} \\ &= \begin{pmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}^{-1} = \underline{\underline{\begin{pmatrix} -1 & -\frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix}}} \end{aligned}$$

Method 2: Using stacking method.

According to the definition of eigenvectors and eigenvalues,

$$Au_1 = \lambda_1 u_1, \quad Au_2 = \lambda_2 u_2, \quad Au_3 = \lambda_3 u_3.$$

$$\Rightarrow A(u_1 \ u_2 \ u_3) = (\lambda_1 u_1 \ \lambda_2 u_2 \ \lambda_3 u_3)$$

Since u_1, u_2 and u_3 are 3 linearly independent vectors in \mathbb{R}^3 ,

$$A = (\lambda_1 u_1 \ \lambda_2 u_2 \ \lambda_3 u_3) \cdot (u_1 \ u_2 \ u_3)^{-1}$$

$$= \begin{pmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}^{-1} = \underline{\underline{\begin{pmatrix} -1 & -\frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix}}}$$

Method 3. Using the standard basis vectors.

From the given information, we get

$$T(u_1) = \lambda_1 u_1 = u_1, \quad T(u_2) = \lambda_2 u_2 = 0_{3 \times 1}, \quad T(u_3) = \lambda_3 u_3 = -u_3$$

$$\Rightarrow T(e_1) = T(u_3) = -u_3 = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} T(e_2) &= T((u_3 - u_2 + u_1) \cdot \frac{1}{2}) = \frac{1}{2}(T(u_3) - T(u_2) + T(u_1)) \\ &= \frac{1}{2}(-u_3 - 0_{3 \times 1} + u_1) = \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \end{aligned}$$

$$\begin{aligned} T(e_3) &= T(u_1 - e_2) = T(u_1) - T(e_2) \\ &= \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}. \end{aligned}$$

$$\Rightarrow A = (T(e_1) \ T(e_2) \ T(e_3)) = \underline{\underline{\begin{pmatrix} -1 & -\frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix}}}$$